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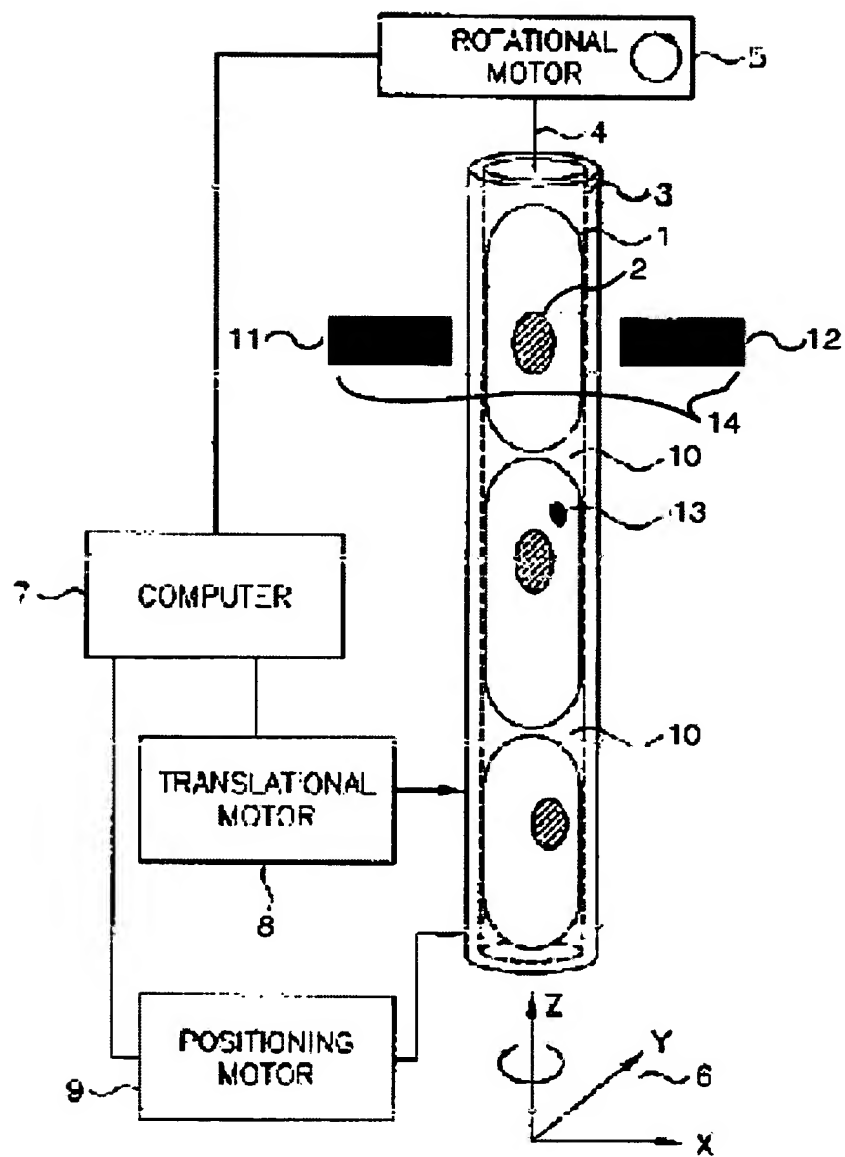


FIGURE 1

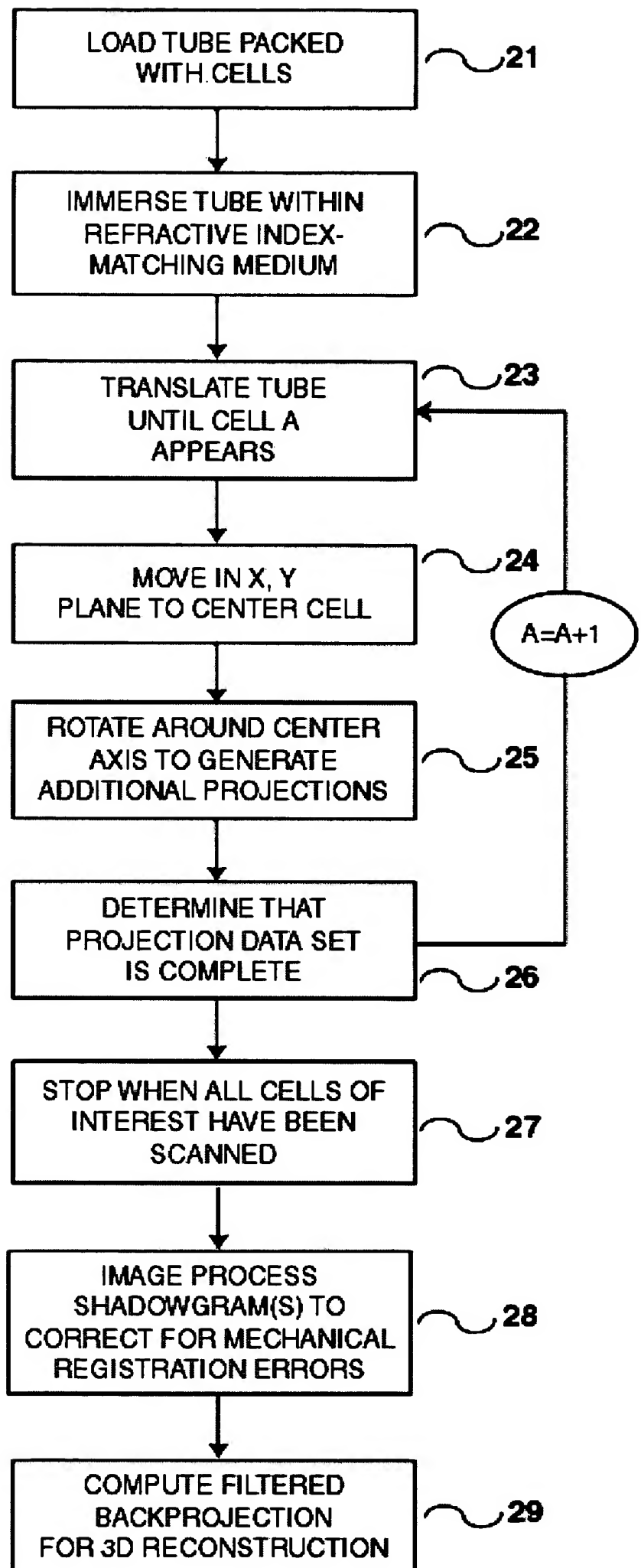


FIGURE 2

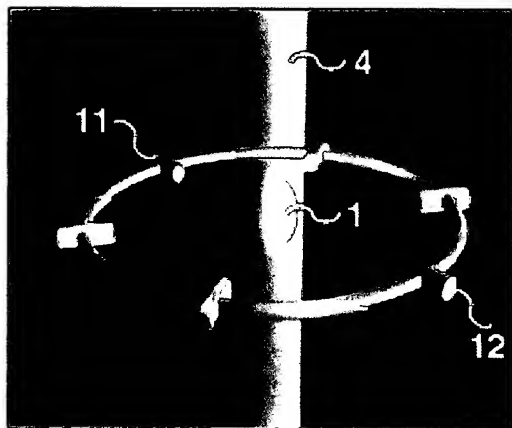


Figure 3A

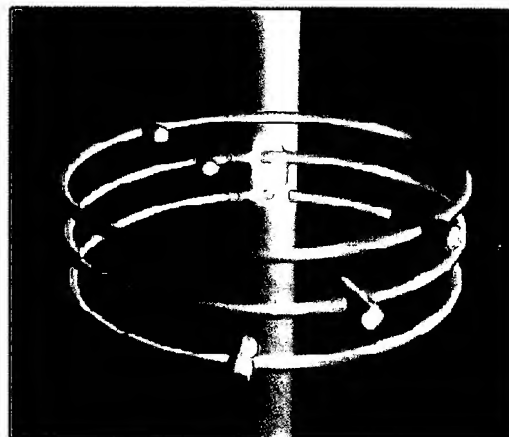


Figure 3B

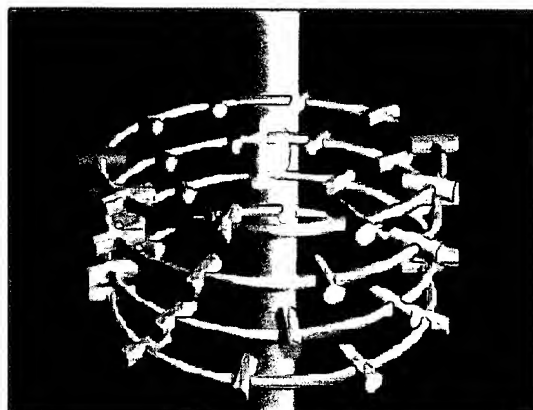


Figure 3C

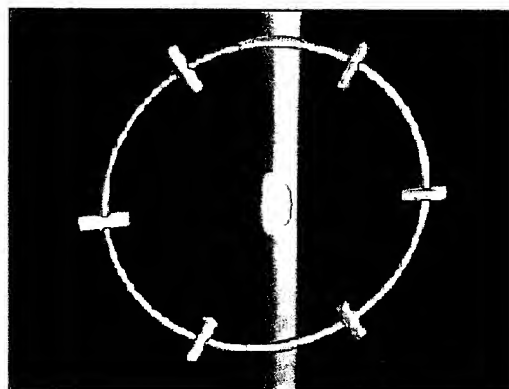


Figure 3D

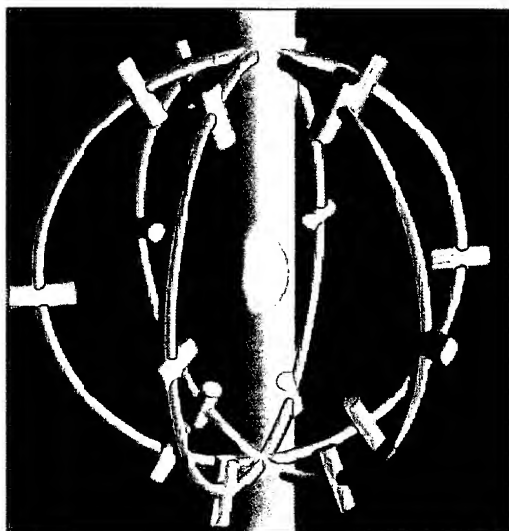


Figure 3E

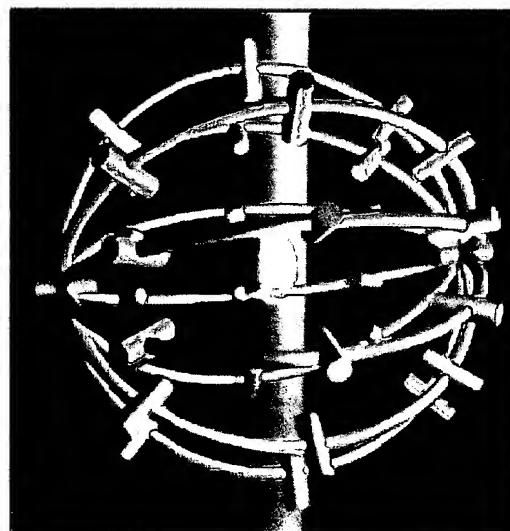


Figure 3F

FIGURE 4A

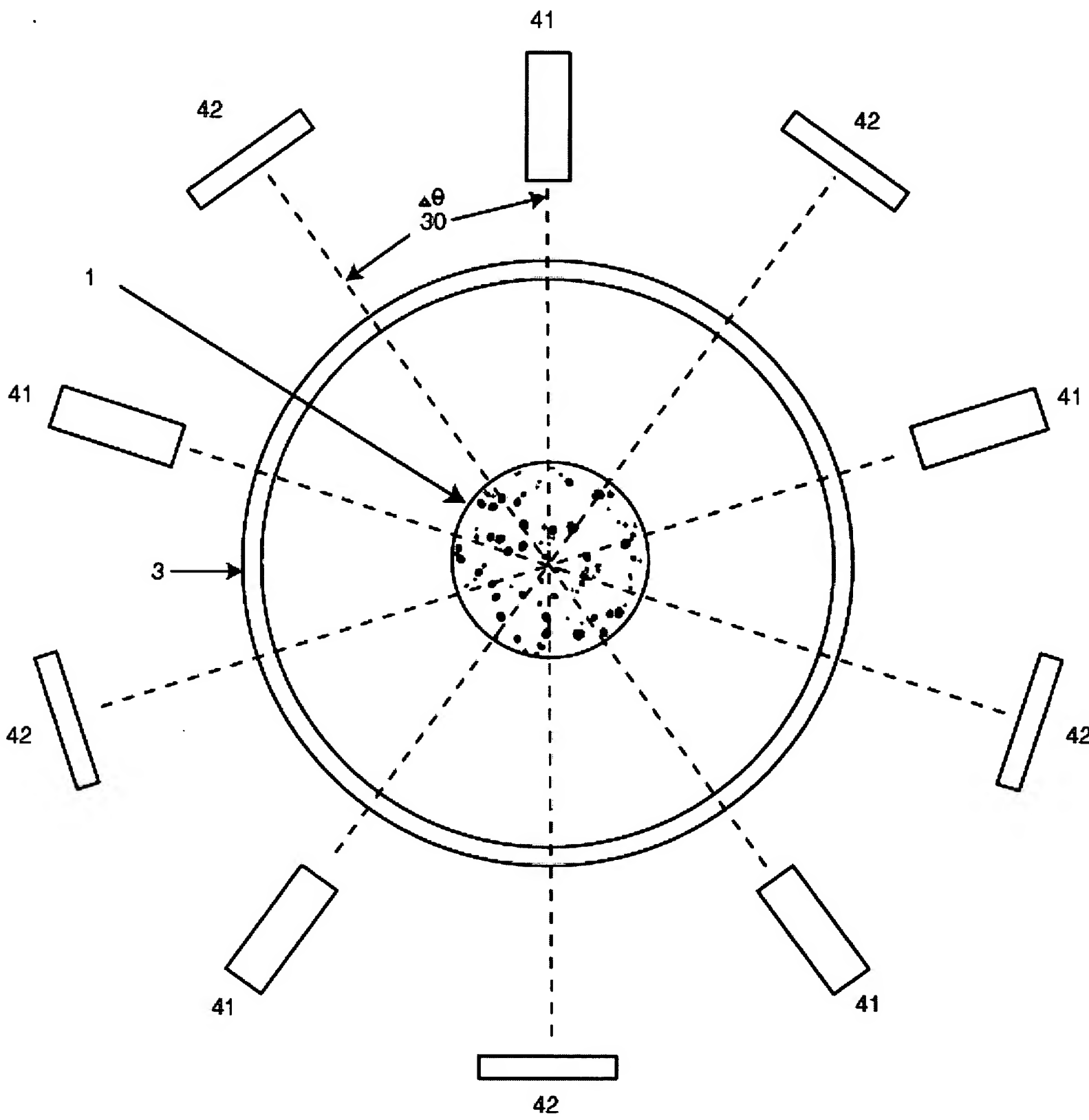
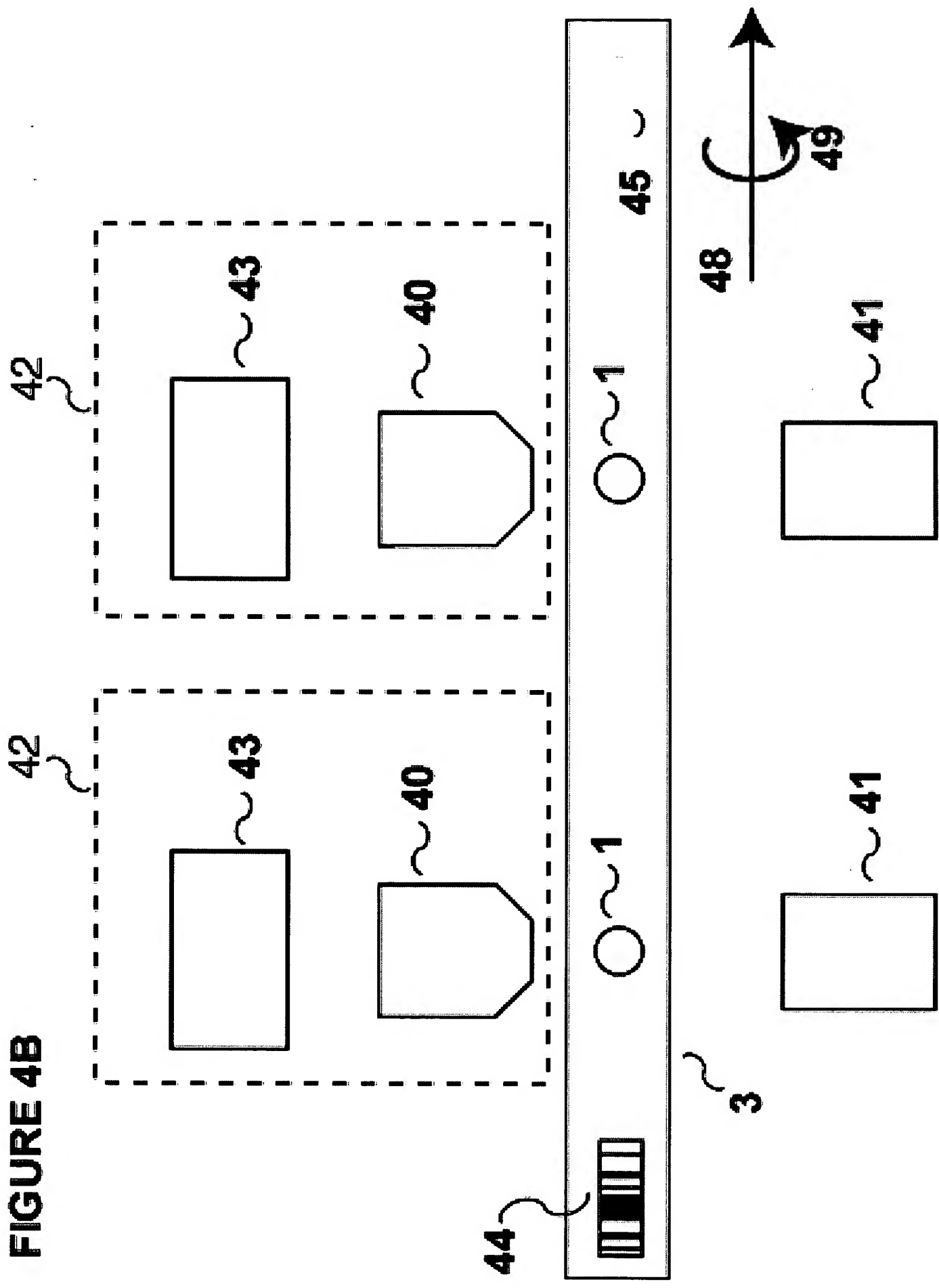


FIGURE 4B



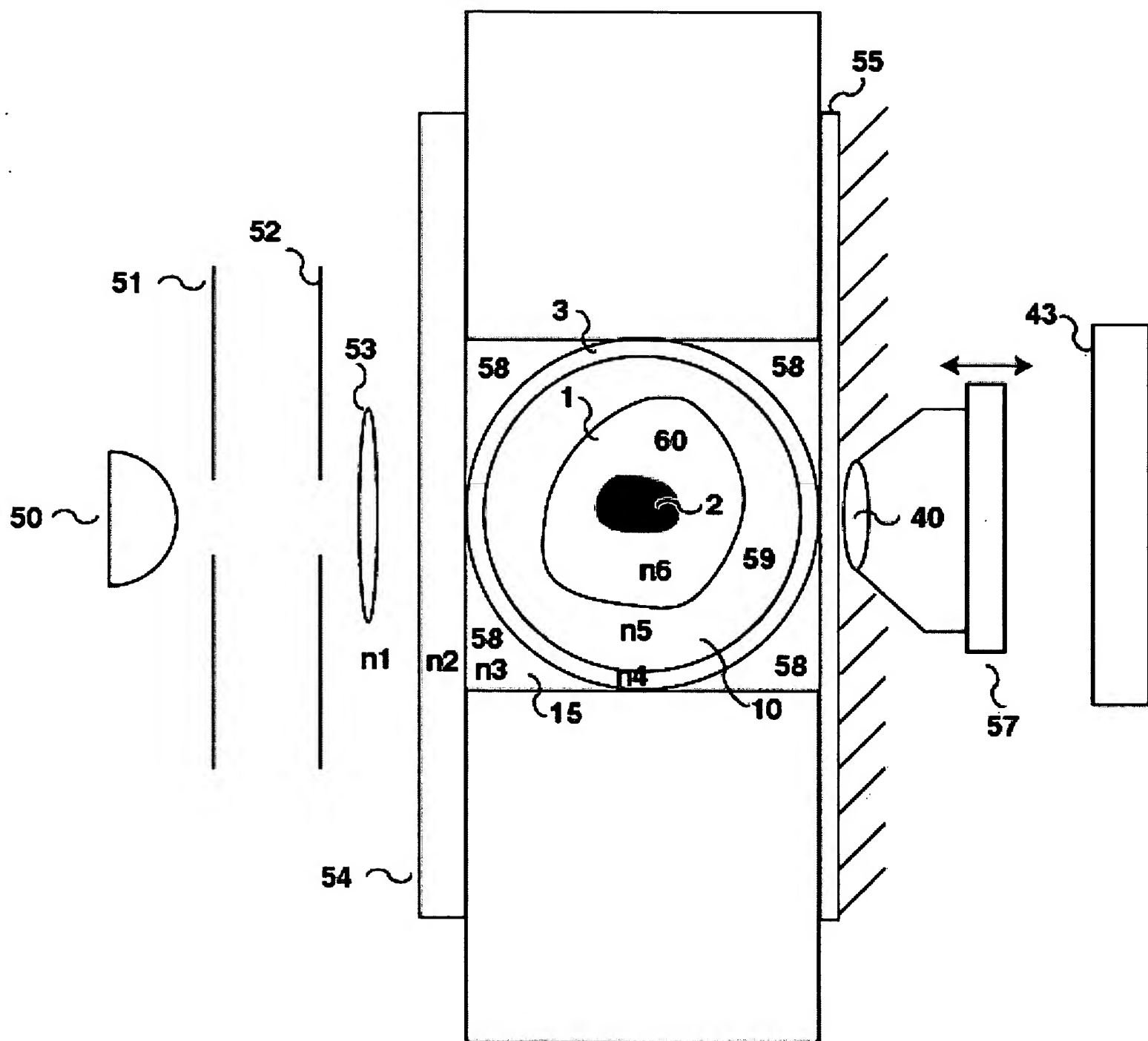


FIGURE 5A

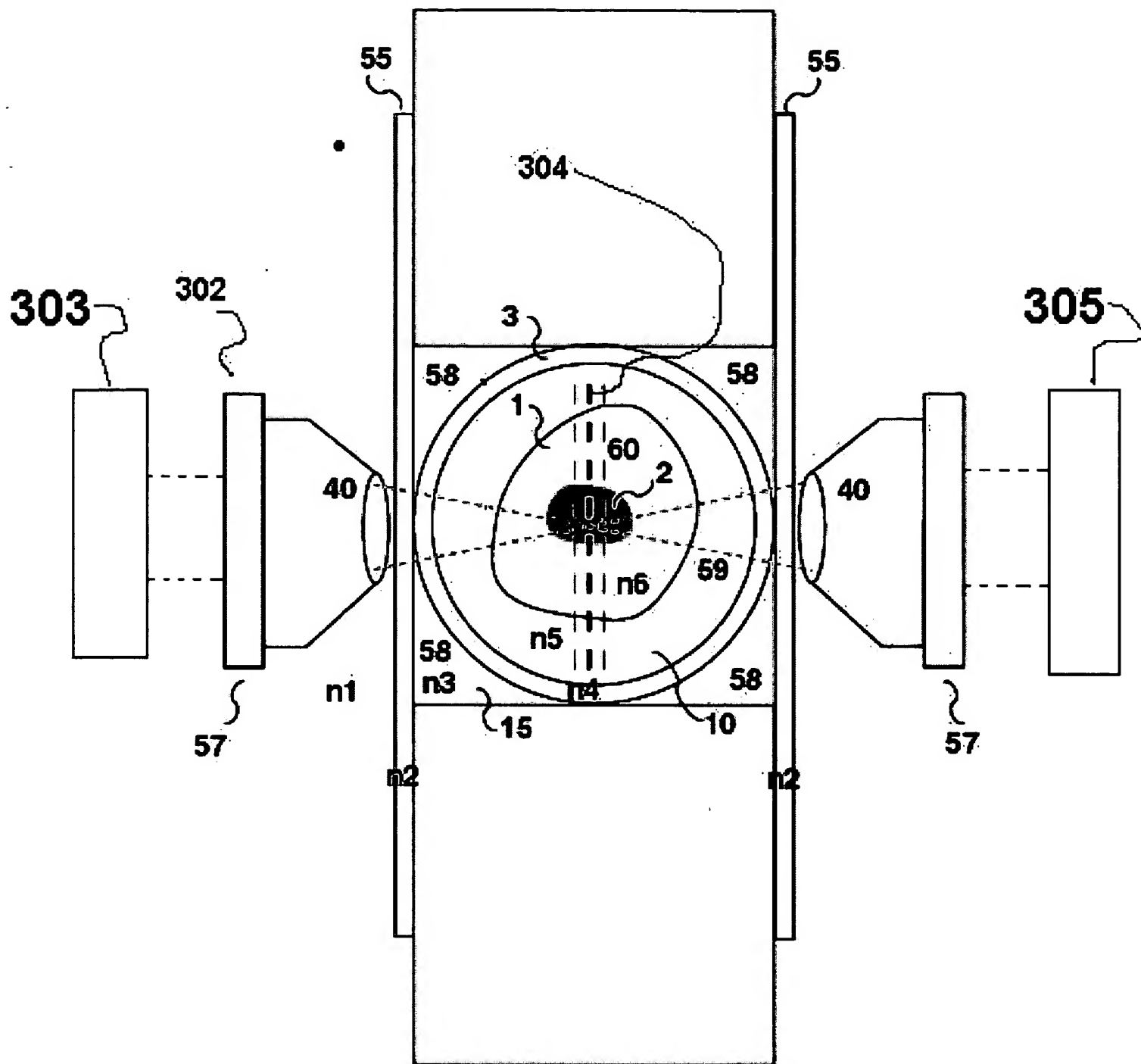


FIGURE 5B

FIGURE 6A

← c mputer 7

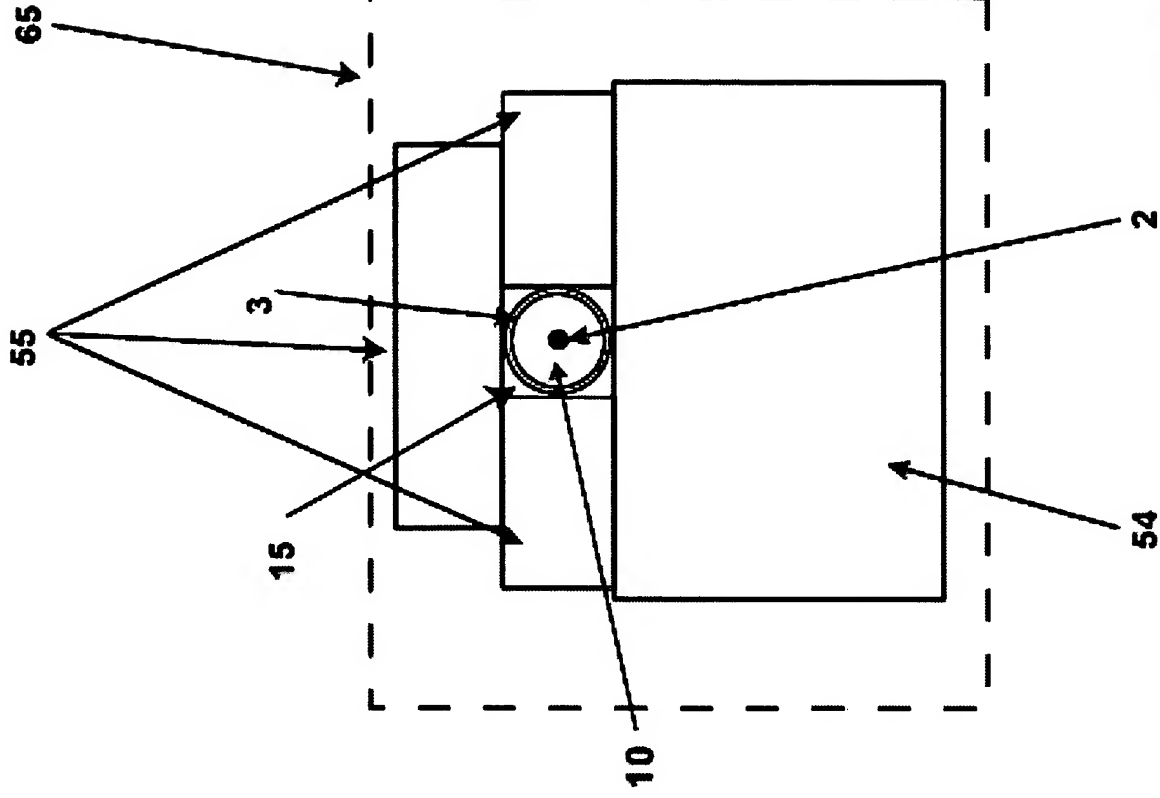
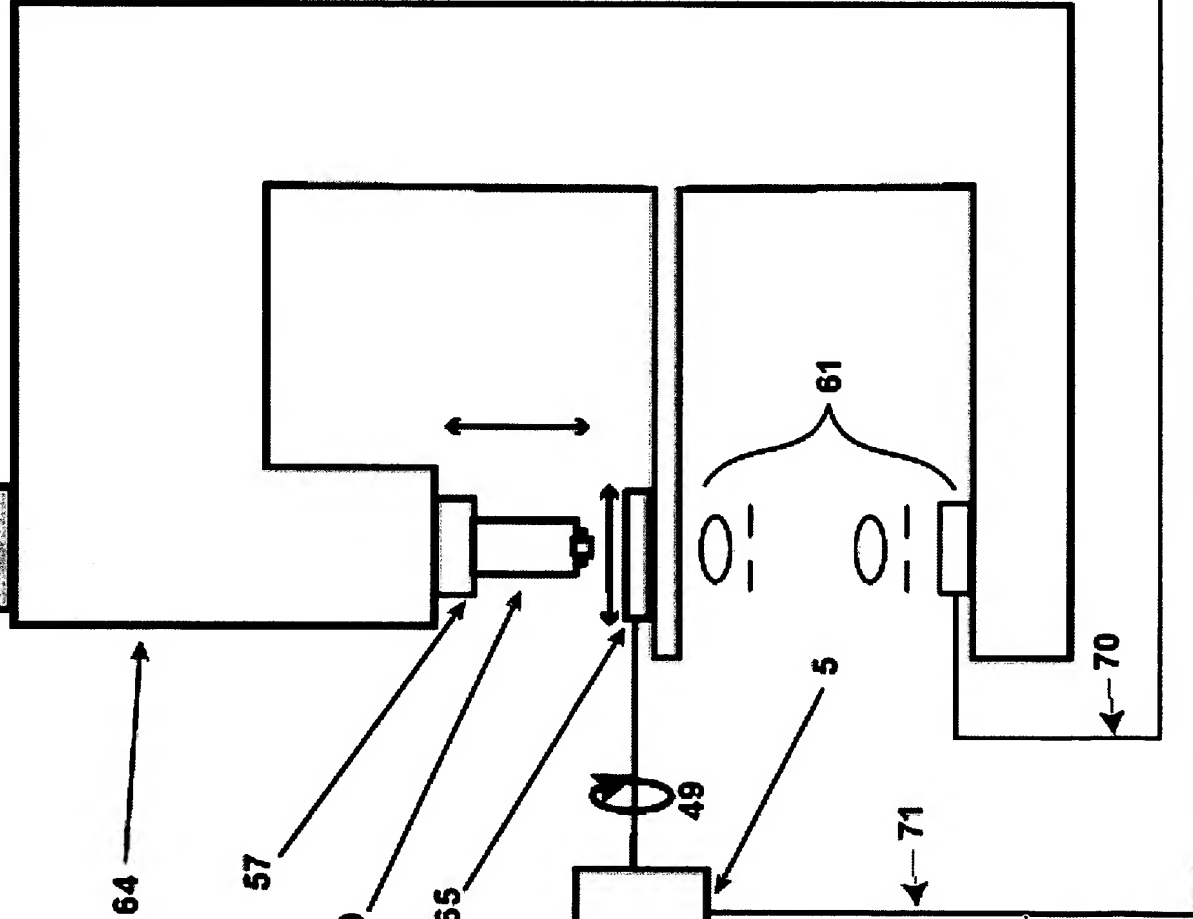
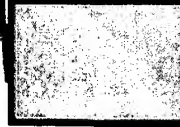
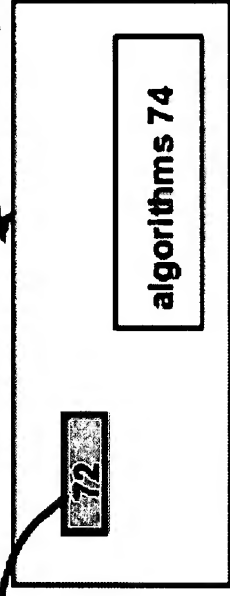


FIGURE 6B

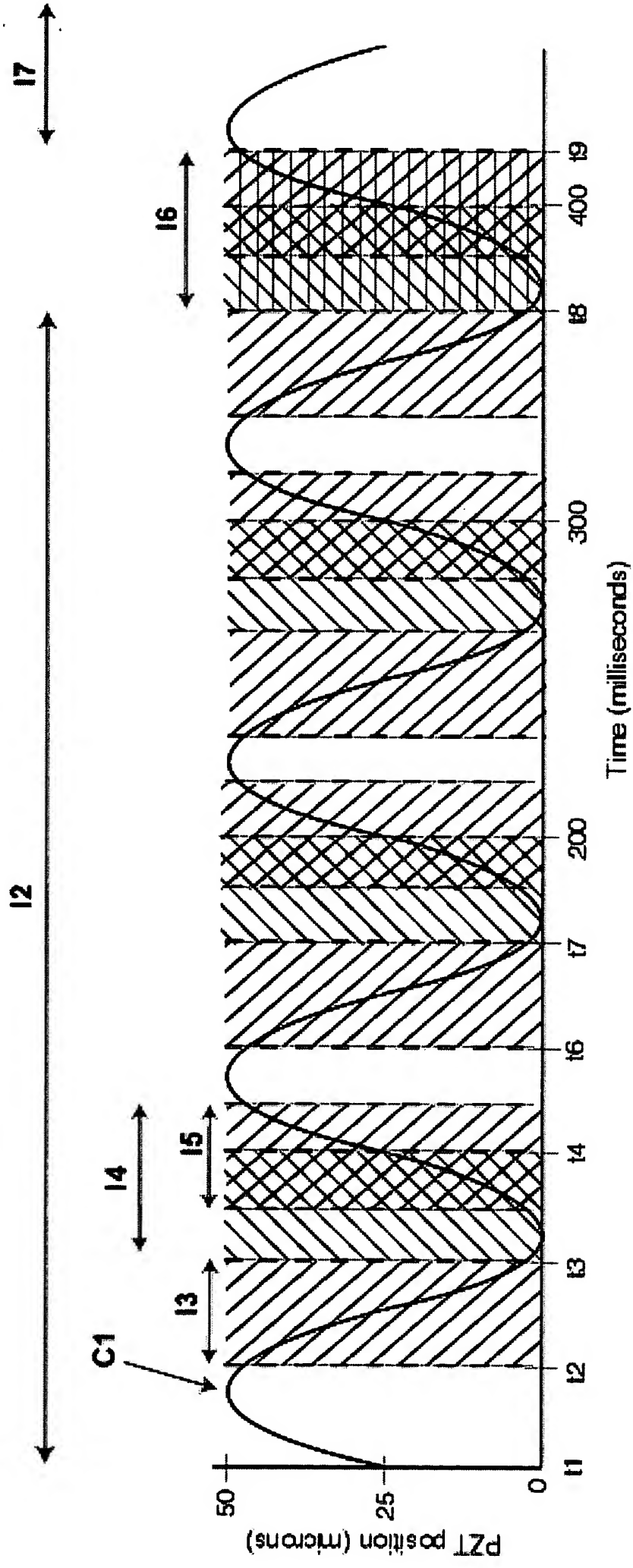
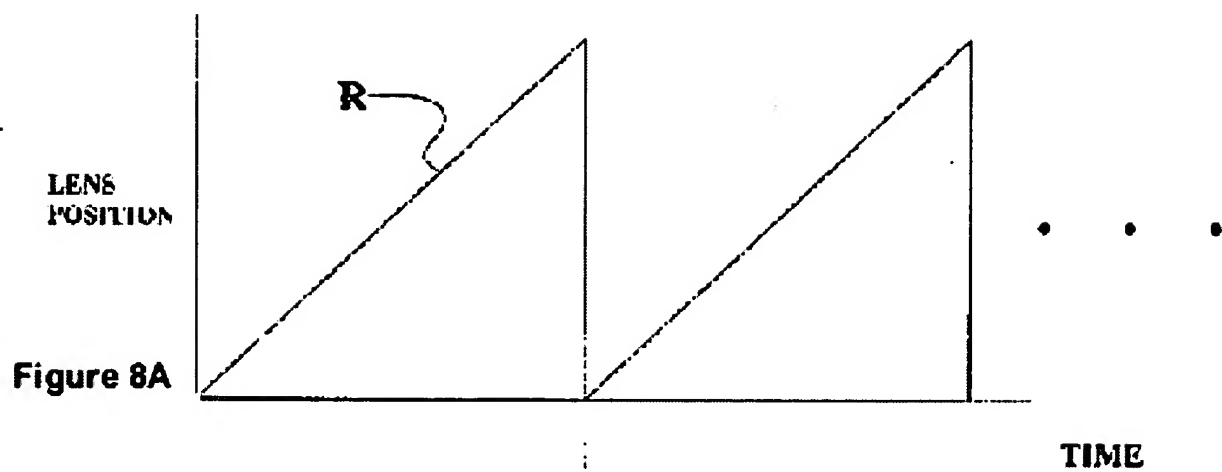


FIGURE 7



Camera Integration

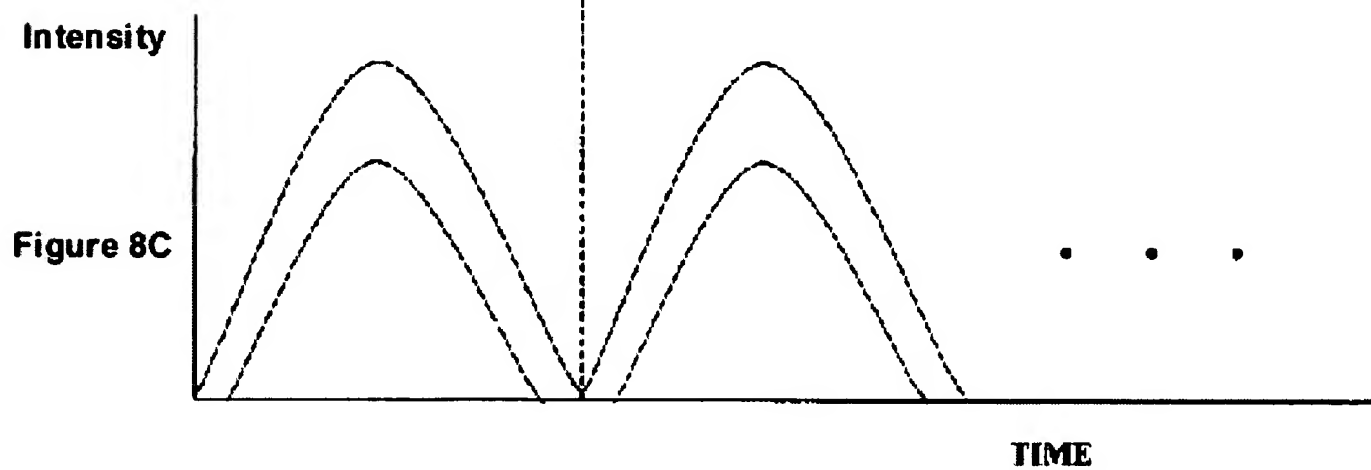
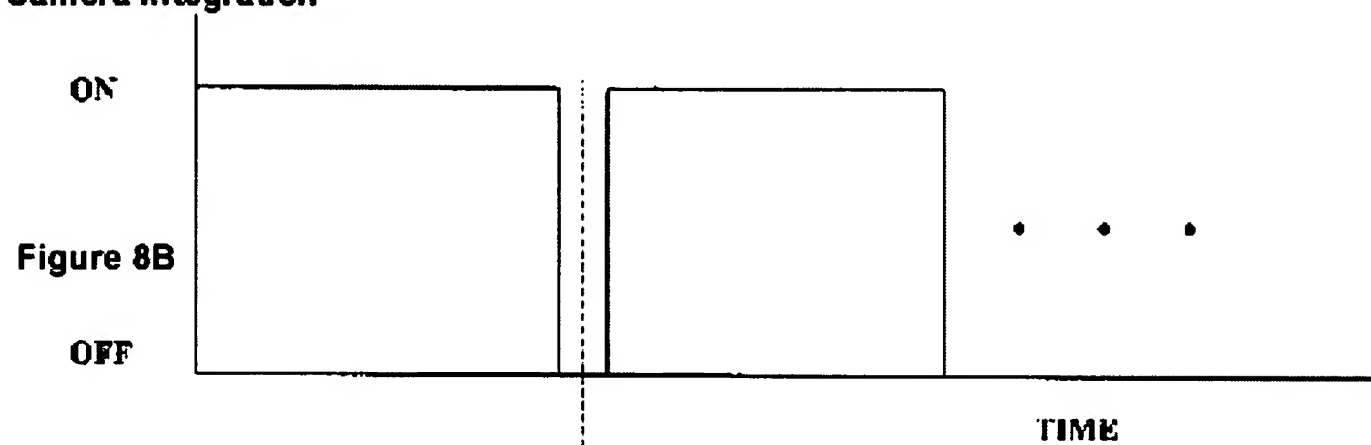


FIGURE 9 (PRIOR ART)

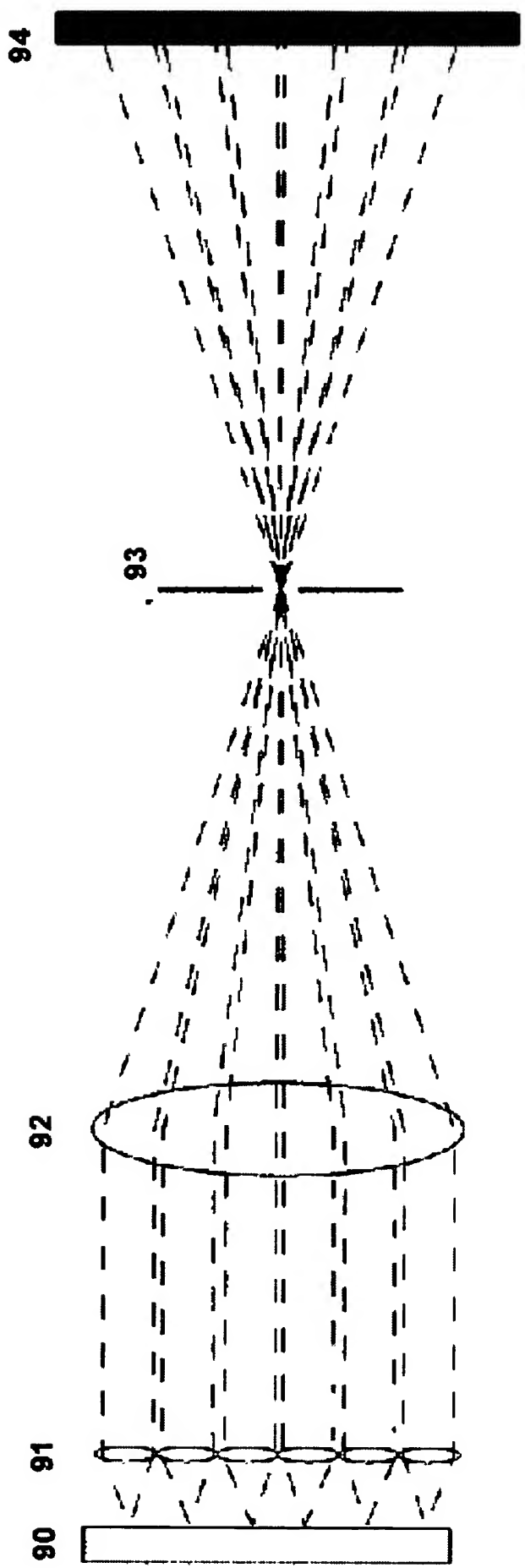
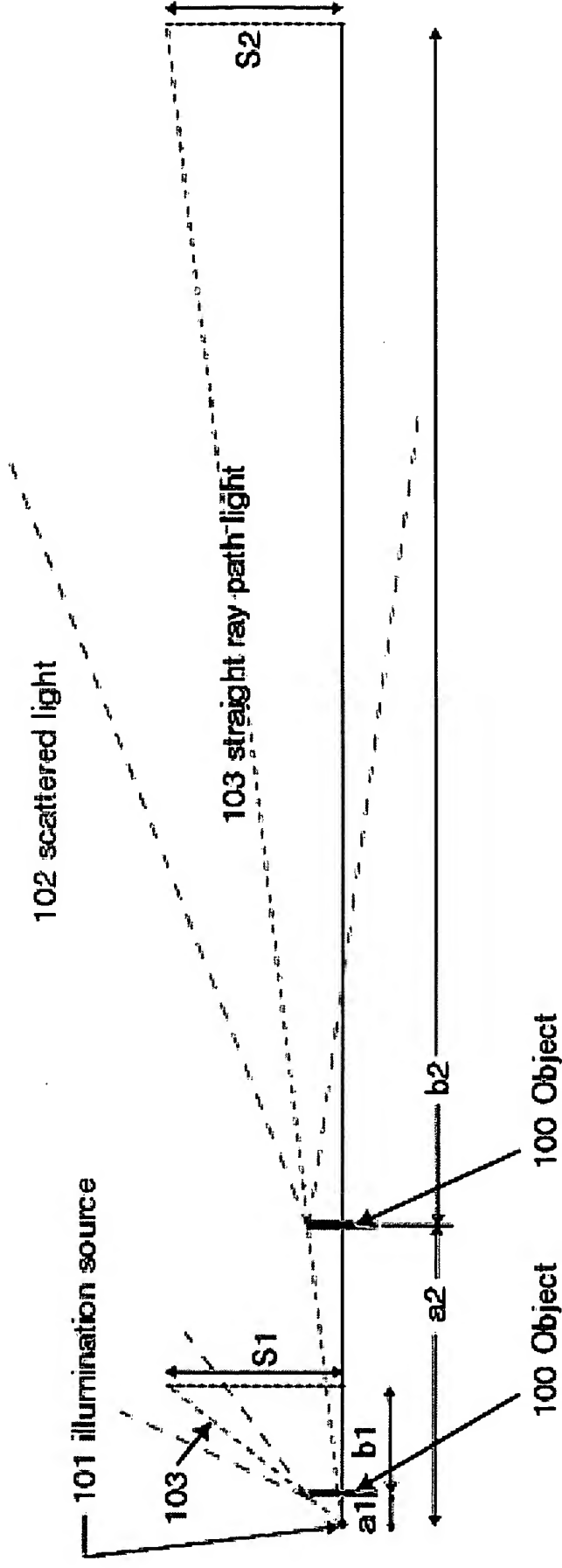


Figure 10



Magnification $M = (a_1 + b_1) / a_1 = (a_2 + b_2) / a_2$

Figure 11.

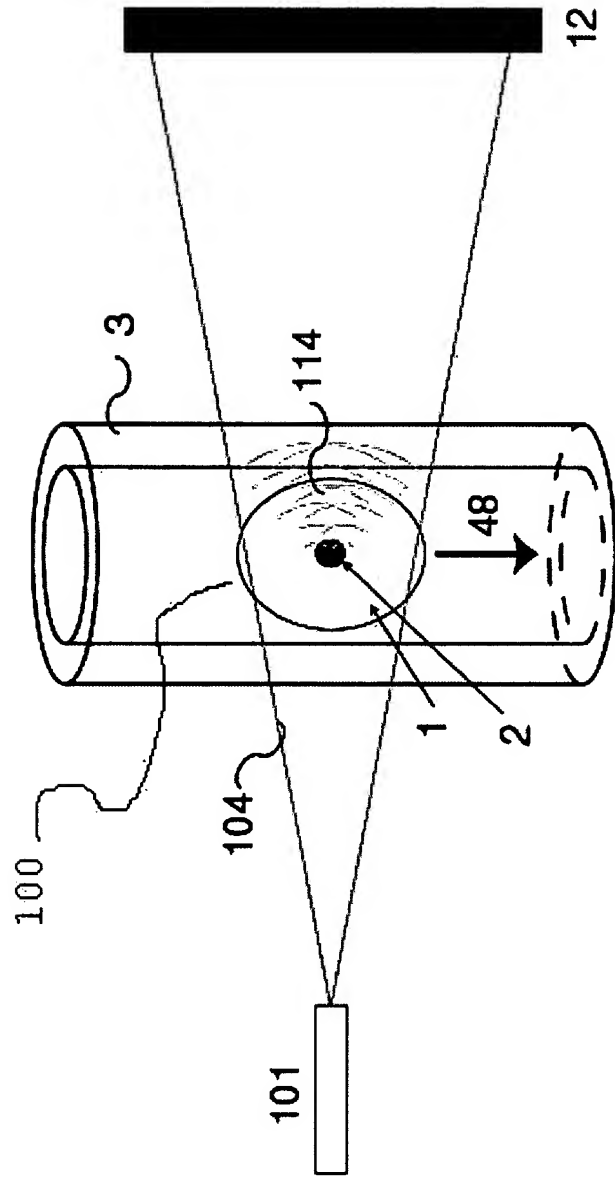


Figure 12.

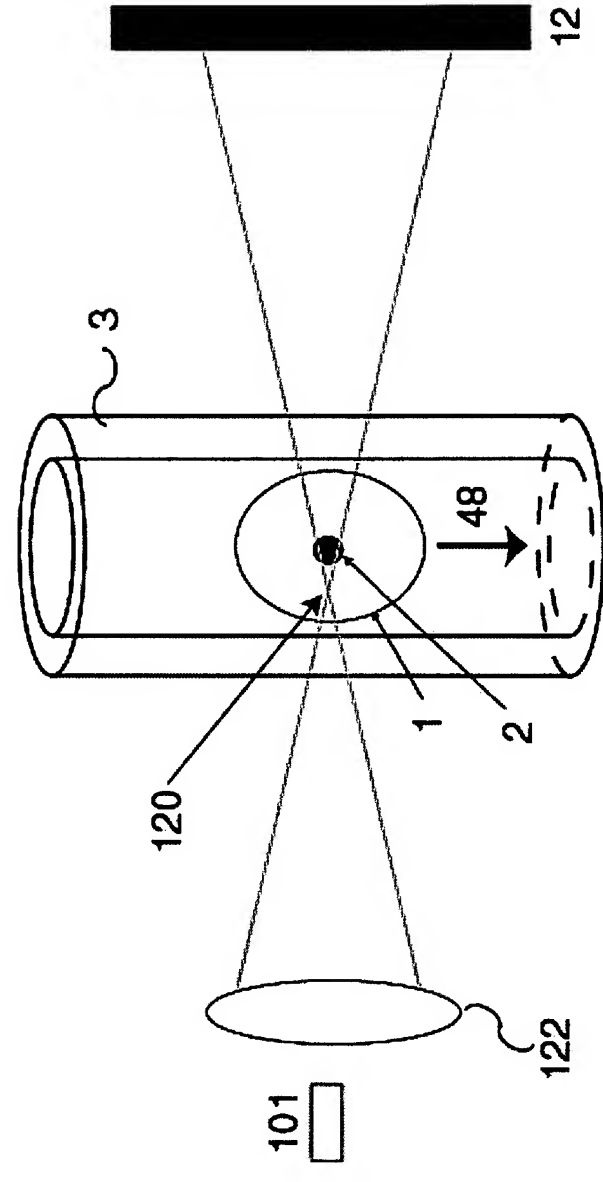


Figure 13A

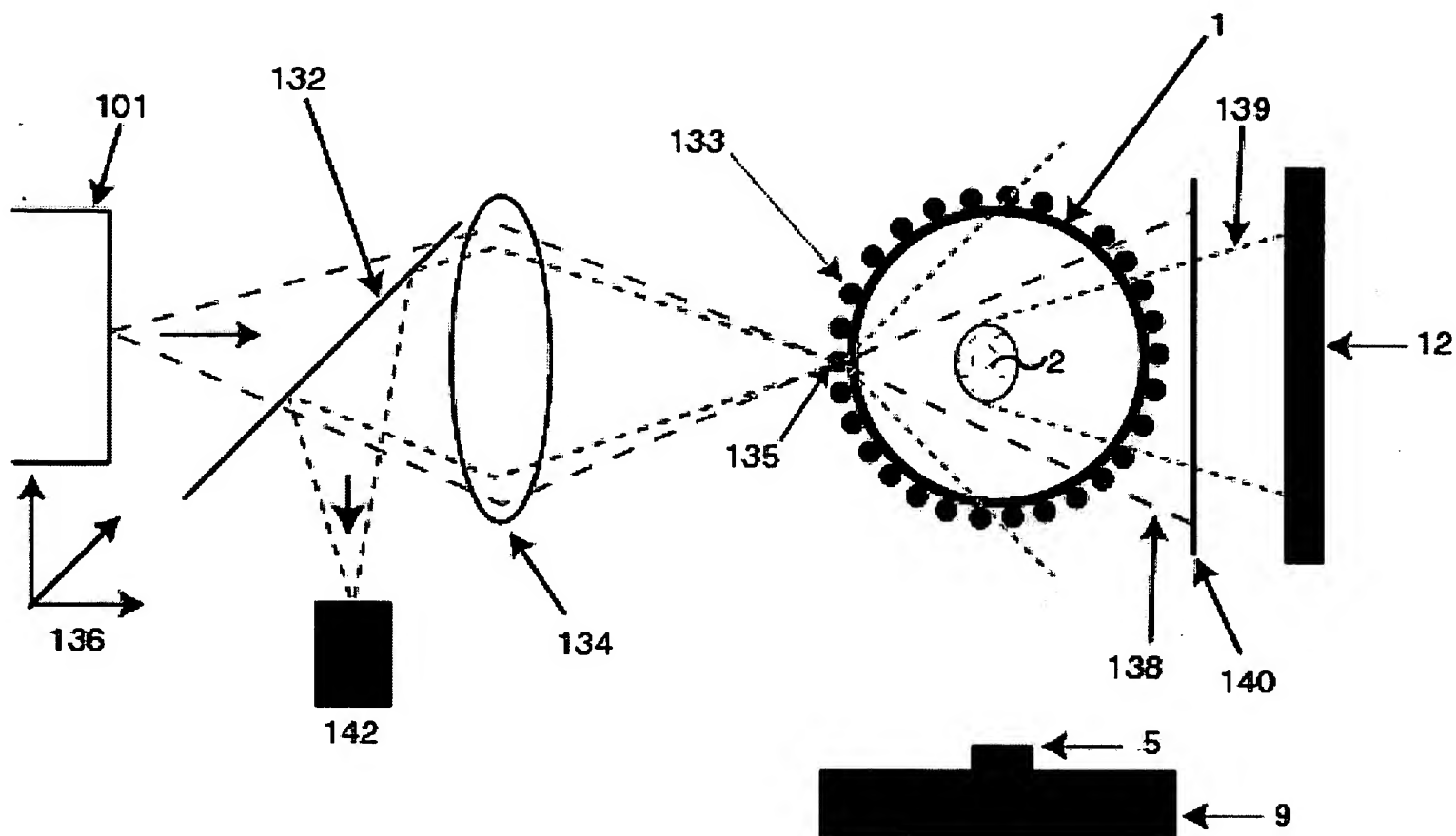


Figure 13B

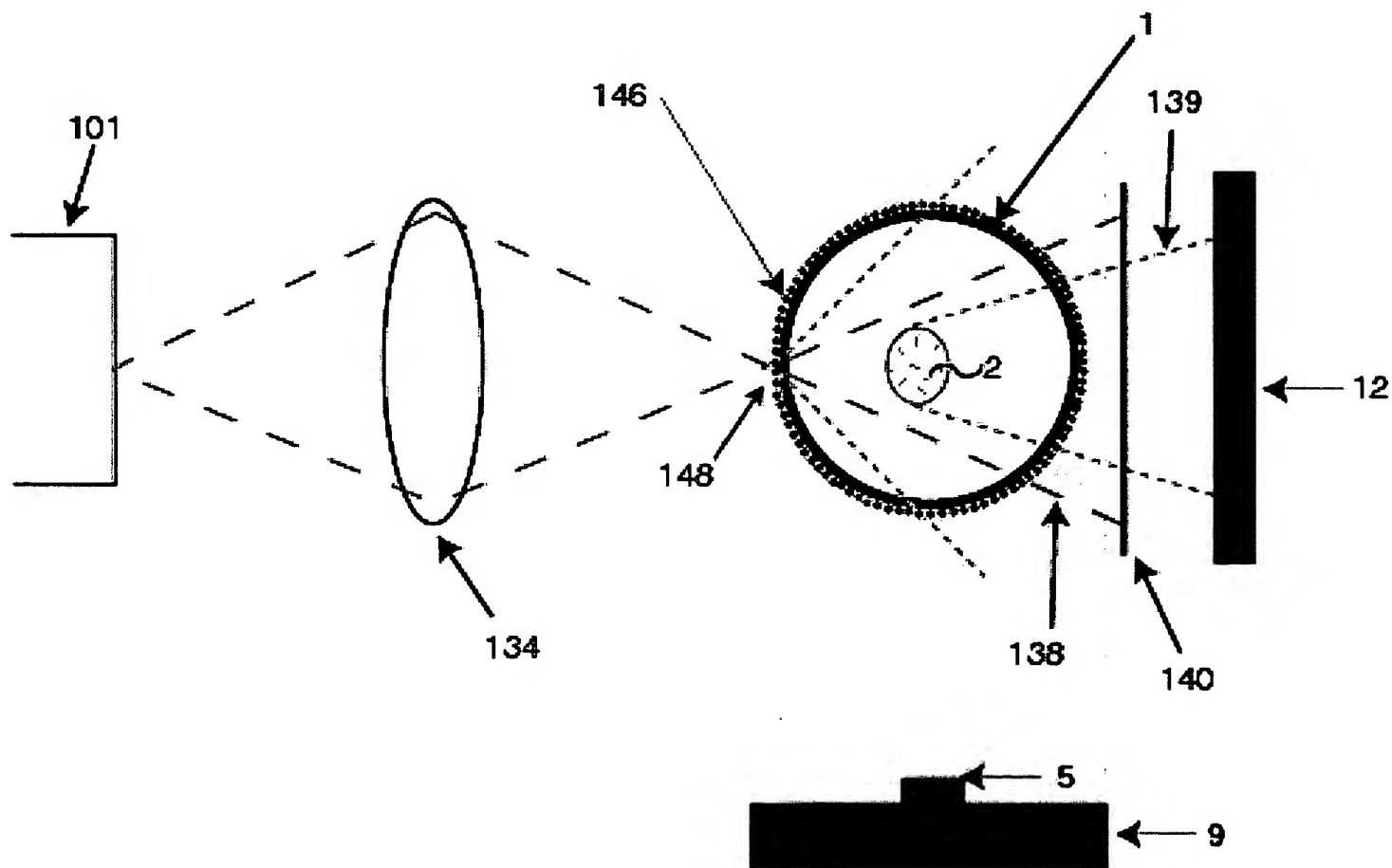


Figure 14A

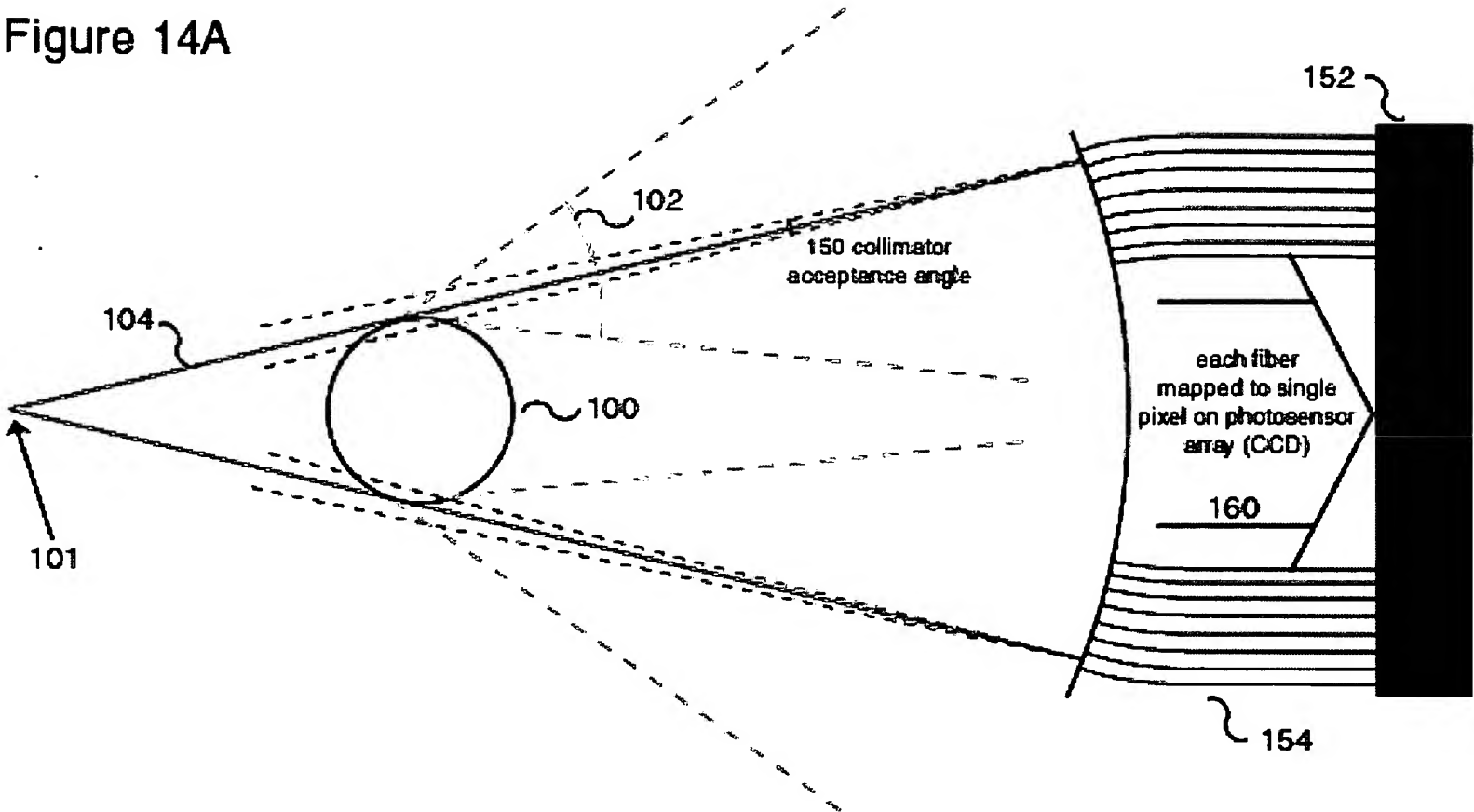


Figure 14B

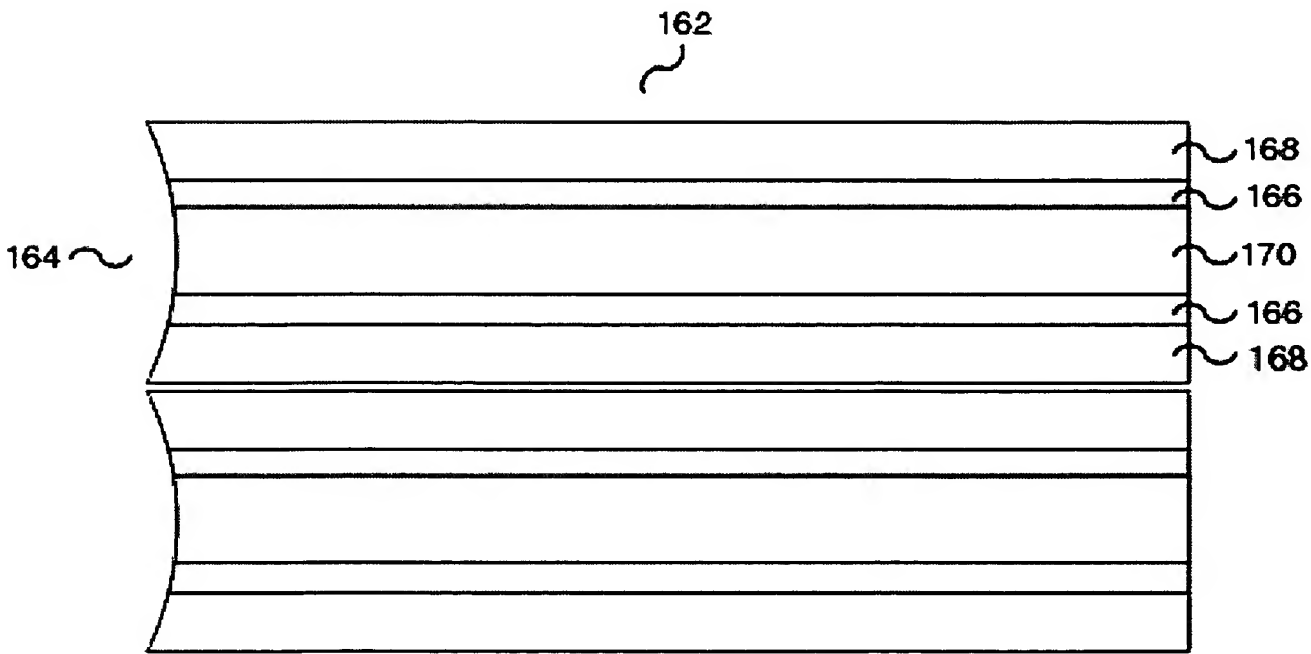


Figure 15A

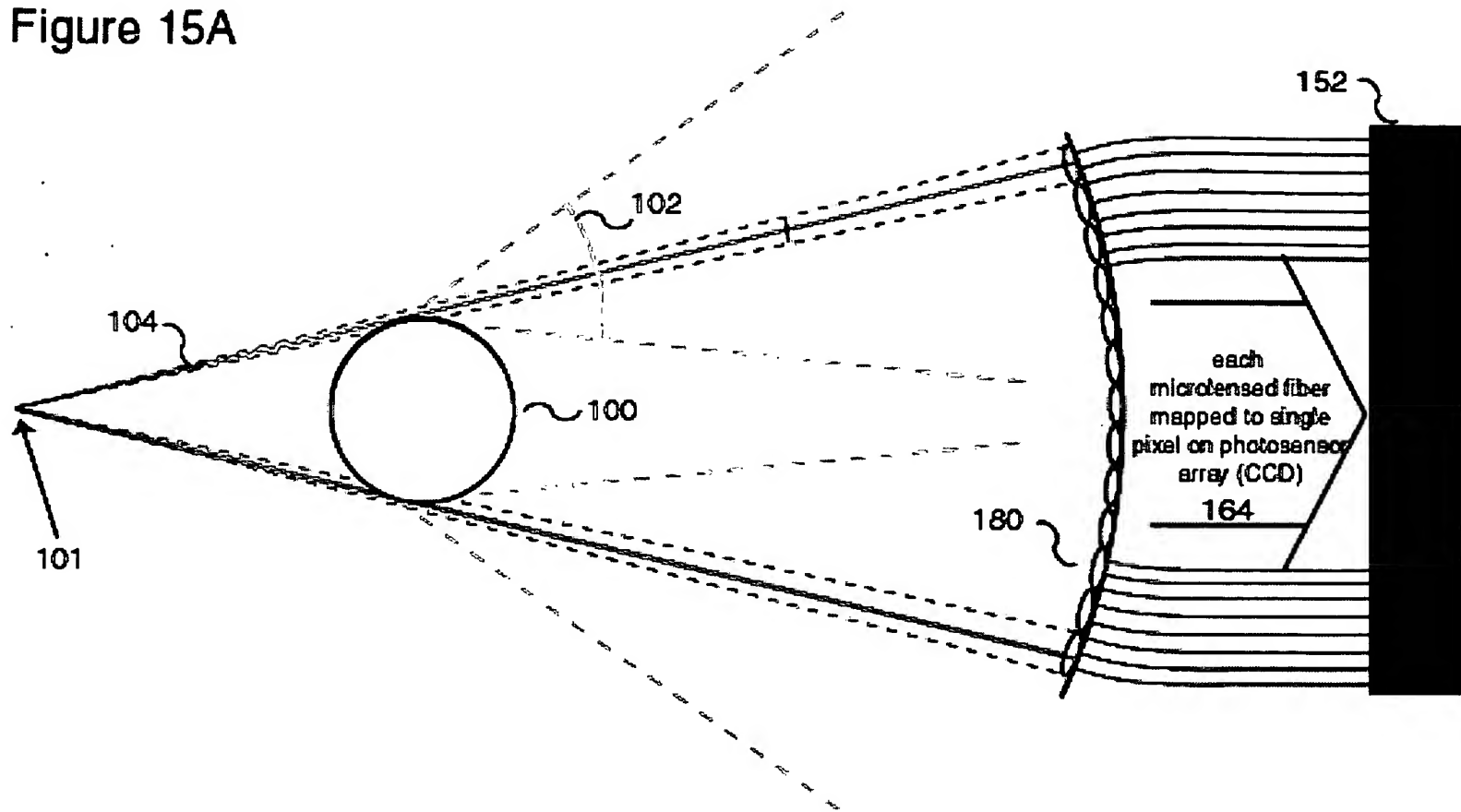
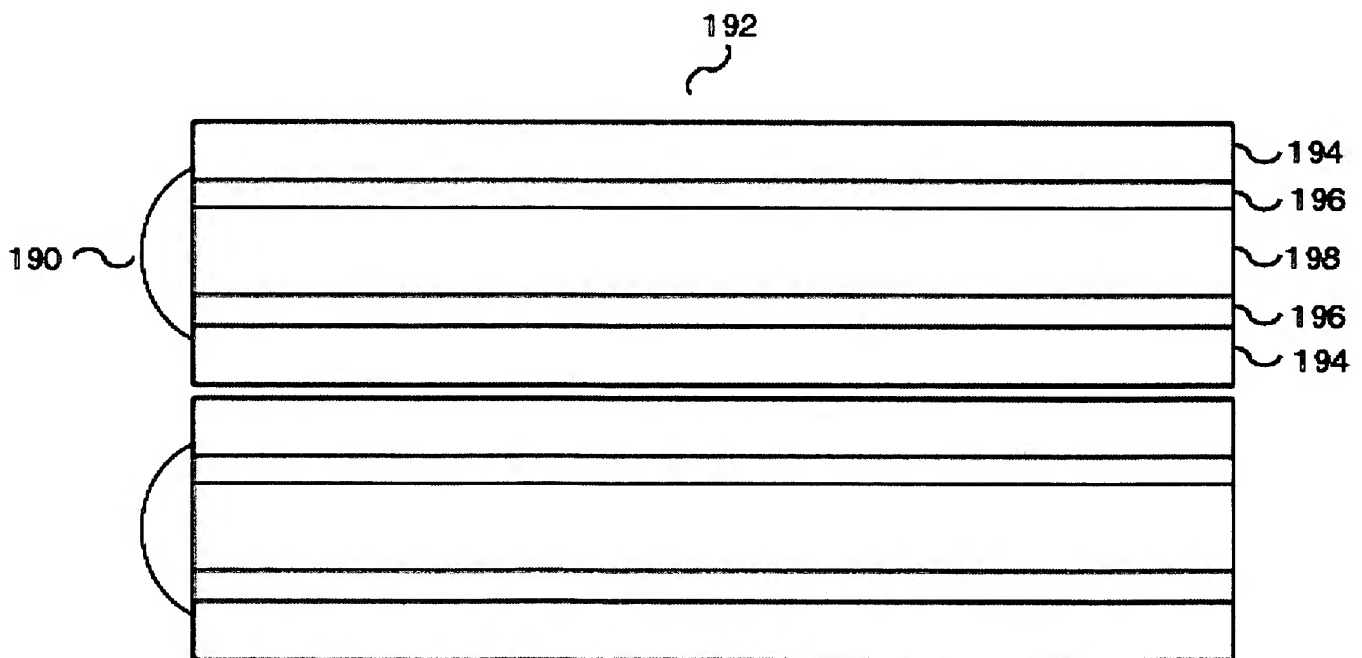


Figure 15B



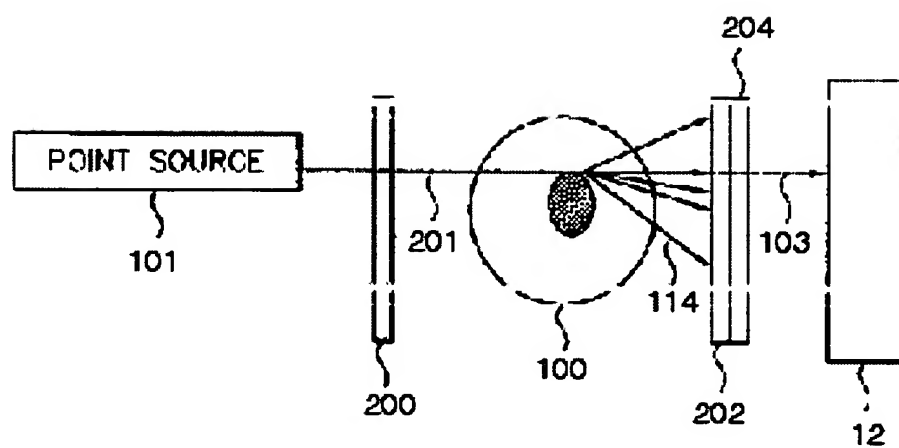


FIGURE 16

Figure 17.

